

Equilibrium $\begin{cases} \rightarrow \text{Particle (2-D)} \\ \rightarrow \text{Particle (3-D)} \end{cases}$

\Rightarrow Equilibrium of Rigid body

1) 2-D

1) Definition of R.B & Description of problem

R.B \rightarrow Body has dimensions \rightarrow area

and the forces, free couples are distributed on the body (Not connected at one point)

2) Equation = Rules

Types of motion

3-types of motion $\begin{cases} \text{along x-dir} \rightarrow \text{translation} \\ \text{along y-dir} \rightarrow \text{translation} \\ \text{Rotation} \end{cases}$

1) $\sum F_x = 0$

prevent x motion

2) $\sum F_y = 0$

No motion along y

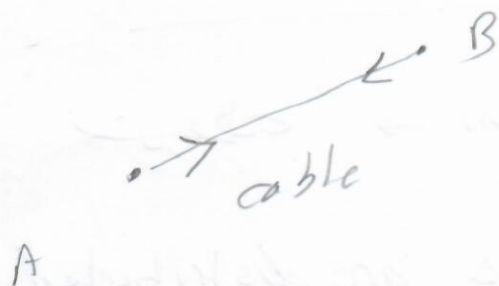
3) $\sum M_{\text{all forces + free couples}} = 0$ No Rotation
@ any point

3) Types of unknowns

7.2

3-1) Tension inside cables or cords and forces in rods

⇒ In rods assume internal force as Tension (T)

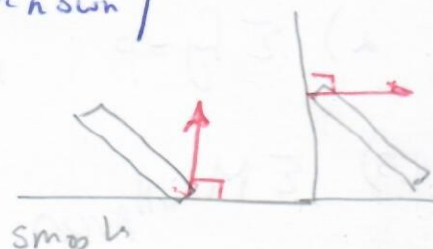


3-2) Reactions at external supports

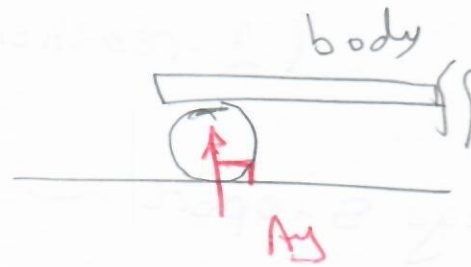
Supports device to prevent motion by reaction

3-2-1 Support prevents one-motion
(one-reaction) (one unknown)

* Smooth contact surface



* Rocker support



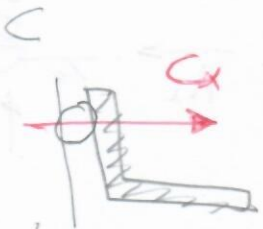
* Roller support

body

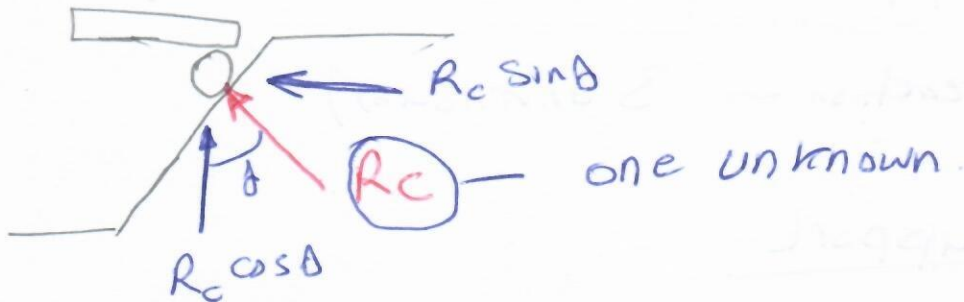


allow
move
horizontal

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allow
move
vertical



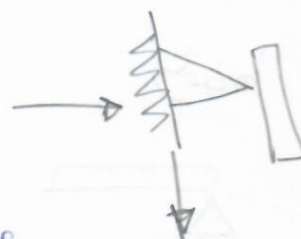
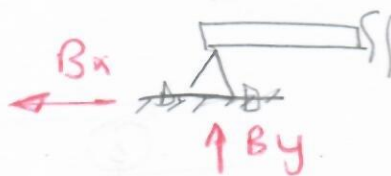
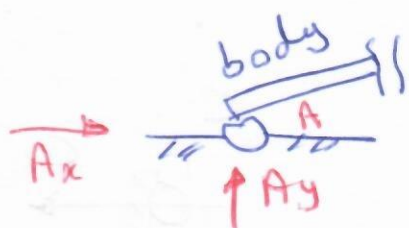
Support has one unknown

⊥ plane of sliding

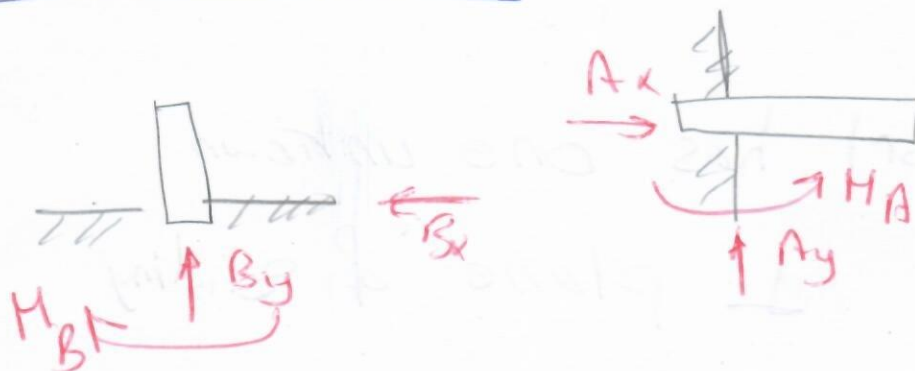
3-2-2 Support prevents 2 motions

(2 reactions - 2 unknown)

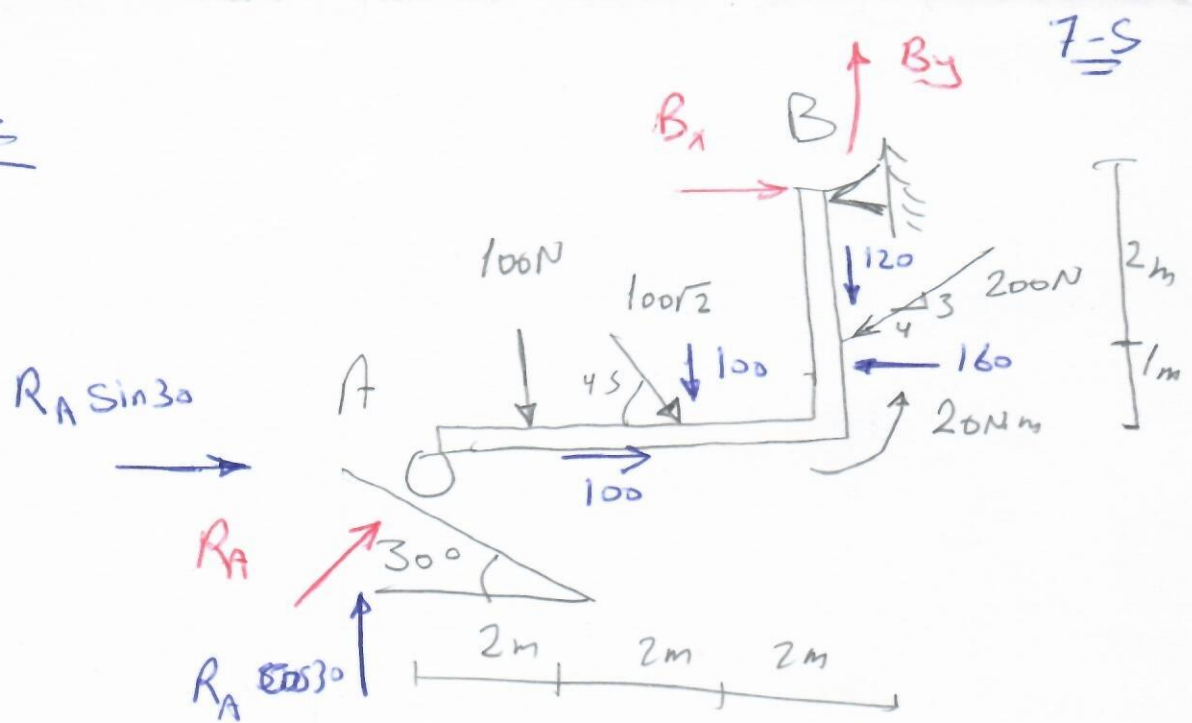
hinge support ~ Pin support

Support has 2 unknowns
x, y3-2-3 Support prevents All motions

(3 reaction - 3 unknown)

Fixed support \Rightarrow 3 unknowns x, y, couple (M)

Example



$$\sum F_x = 0$$

$$R_A \sin 30 + 100 - 160 + B_x = 0 \rightarrow \text{eq (1)}$$

$$\sum F_y = 0$$

$$R_A \cos 30 - 100 - 100 - 120 + B_y = 0 \rightarrow \text{eq (2)}$$

$$\sum M_{\text{all brns}} + \text{couple} = 0$$

↪ moment about point of all unknowns

$$M_B = 0$$

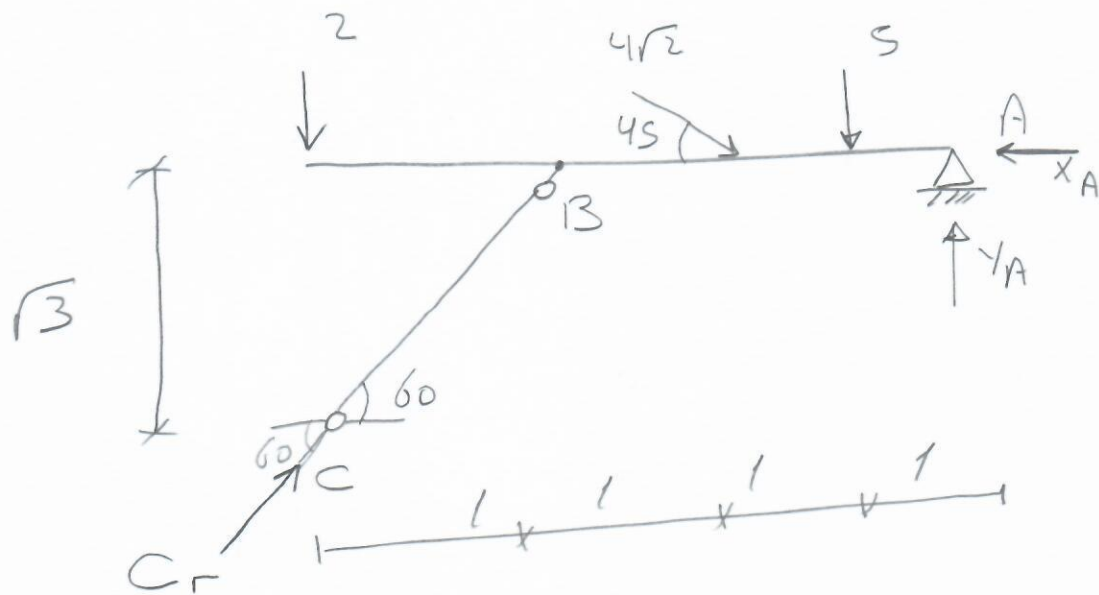
$$(-) -160(2) + 20 + 100(2) + 100(3) + 100(4)$$

$$- R_A \cos(30) (6) + R_A \sin 30 \times 3 = 0 \rightarrow \text{eq (3)}$$

$$\hookrightarrow R_A = \checkmark$$

$$\text{from eq (1)} \rightarrow B_x$$

Example for Link member (2-Force member)



$$\rightarrow \sum F_x = 0$$

$$C_r \cos 60 - X_A + 4\sqrt{2} \times \cos 45 = 0$$

$$\frac{1}{2} C_r - X_A = -4 \rightarrow (1)$$

$$\uparrow \sum F_y = 0$$

$$C_r \sin 60 - 2 - 4\sqrt{2} \sin 45 - 5 + Y_A = 0$$

$$\frac{\sqrt{3}}{2} C_r + Y_A = 11 \rightarrow (2)$$

$$\curvearrowright + \sum M_A = 0$$

$$-C_r \cos 60 \times \sqrt{3} + C_r \sin 60 \times 4 - 2 \times 4 - 4 \times 2 - 5 \times 1 = 0$$

$$C_r = \frac{14\sqrt{3}}{3} = 8.08 \text{ N}$$

$$\therefore X_A = 8.041 \text{ N}$$